Feedback Control Of Dynamic Systems 6th Solutions Manual



Feedback Control Of Dynamic Systems

An Understandable Introduction to Digital Control. Feedback Control of Dynamic Systems provides enough information, early and simply, so that a student can implement a controller in a digital computer, and an instructor can cover it in one lecture.

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In Section 8.1 we describe the basic structure of digital control systems and introduce the issues that arise due to the sampling. The digital implementa tion described in Section 4.4 is sufficient for implementing a feedback control law in a digital control system, which you can then evaluate via SIM.ULINK®

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FEEDBACK EXAMPLES 5. namics in the system (parameter errors, unmodeled effects, etc). The algorithm that computes the control action as a function of the sensor values is often called a control law. The system can be influenced externally by an operator who intr o- duces command signals to the system.

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